

SPID Azimuth & Elevation Antenna rotator **P/N: RAS/HR**



SPID RAS/HR MD-02 Rotor Controller



keyboard

Display 2 x 20

ON/OFF Power

Type RAS/HR is a 2 engine rotor system (Azimuth & Elevation) and supplied including:

- ✓ **RAS/HR rotor 0.2 degree resolution**
- ✓ **MD-02 rotor controller (at request MD-01, 19" rack mount model)**
- ✓ **Software to control MD-02 rotor controller from PC**
- ✓ **USB connection for PC**
- ✓ **Build in track interface (EME, Satellite, or write own app)**
- ✓ **All connectors to connect to rotor and PS-02 (Connector rotor side IP-68)**

We recommend to use Power supply module PS-02 to drive the MD-02 and Rotor.
This module is a dual voltage power supply which will be connected to the MD-02 module

Alle leveringen dienen te worden betaald binnen 30 dagen na factuurdatum. Voor alle door ons gesloten overeenkomsten, leveringen en diensten gelden onze algemene verkoop en leveringsvoorwaarden welke op www.rfhamdesign.com zijn vermeld.
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Short summary specifications:

Type RAS/HR is configured with a electronic sensor in order to indicate the position of **Azimuth & Elevation with a resolution of 0.2 degree** (transmission is 0,125 degree on impulse)

The MD-02 rotor controller has a build in backlight Display which shows Azimuth & Elevation real time at 0.2 degree resolution. This means the rotor can also be used as a stand-alone configuration and the Azimuth & Elevation engine can be moved using the arrow buttons at the front.

Also can be the menu be entered and changes can be made to all available functions.

Note: The MD-02 controller can handle 2 rotor systems, this means you can also drive 2 pcs Azimuth or 2 Elevation rotators at the same time !

Build in the MD-02 rotor controller is also a track interface which will be connected through USB (Win XP....Win 7, 8) USB Driver is available and ready for download at our /HR support page. (/HR = High Resolution)

Lot's of new functions are available now and can be configured by the user through MD01dde.exe PC interface:

MD-01 Interface (Picture right) can be used to control the AZ & EL rotor by Personal Computer.

One of the most used track program Orbitron is integrated to select easy.
(more info at the SPID /HR support page)



More available functions:

- ✓ Most used and special function is the integrated function: Soft Start and Soft Stop !
Soft start and stop has available a 3 step Delay time and a 3 step acceleration time. Both Delay and acceleration can be set by the user step by step. This function is very helpful for large dishes
- ✓ Firmware update free of charge
- ✓ Short way function for Satellite track
- ✓ USB controlled
- ✓ Mouse option: control AZ and EL movement by a mouse connected to MD-02
- ✓ Minimum and maximum angle free adjustable for Azimuth and Elevation
- ✓ Write your own protocol and/or PC application (protocol available for download)
- ✓ Ethernet module option (ready to build in)
- ✓ Build in 19" rack system
- ✓ Free of charge software update available at our High Resolution support page (need password to acces)
- ✓ Track software supported: Orbitron and PST rotor (more will be available)
- ✓ MD-01 Rotor Controller can emulate all Yaesu rotor drivers !

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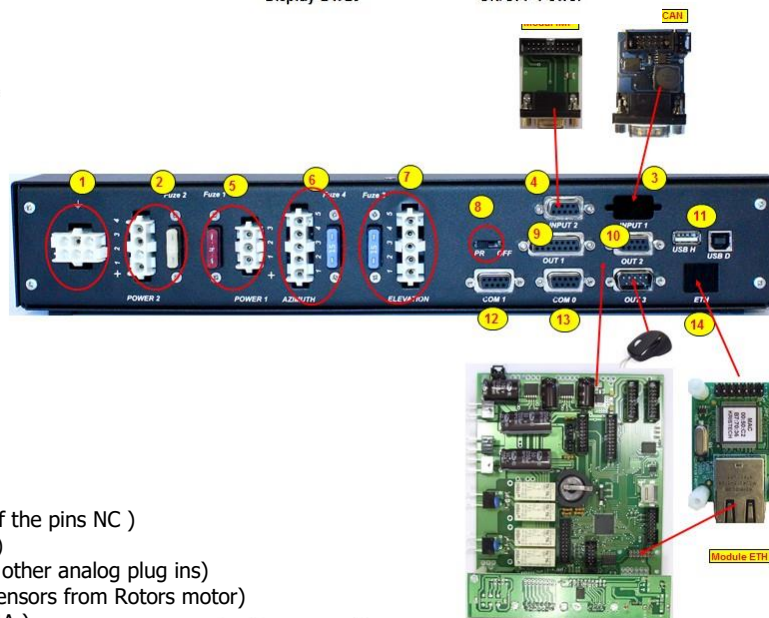
MD-02 Rotor Controller in spotlight



keyboard

Display 2 x 20

ON/OFF Power



Description MD-02:

- 1# Plug in for Ground connecting (rest of the pins NC)
- 2# Plug in for Rotors engine (FUZE 25A)
- 3# NC, (Example CAN, RS485, RS422 or other analog plug ins)
- 4# Impulse plug in (plug in for HALL 4 sensors from Rotors motor)
- 5# Plug in for MD-02 electronics (FUZE 4A)
- 6# Plug out for connecting Rotors type RAK, BIG-RAK or Elevation motors type RAS, BIG-RAS. RAEI
On each plug out there is FUZE (15A)
- 7# Plug out for Rotors RAK, BIG-RAK or azimuth motor RAS, BIG-RAS
On each plug out there is FUZE (15 A)
- 8# Switch for updating Firmware MD-01 / MD-02
In PR position update software by com1, OFF position is normal operation
- 9# Universal plug out . There is possibility to connect relay module inside of the driver .
Driver will have function to antenna switch
- 10# Universal plug out
- 11# USB plug in
USB - D -- DEVICE
USB - H -- HOST (version on future)
- 12# Plug out RS-232
COM 0 (RxD and TxD, it is also plug in for updating)
COM 1 (RxD nad TxD)
- 13# Universal plug in for mouse (option)
- 14# Ethernet plug in (option)

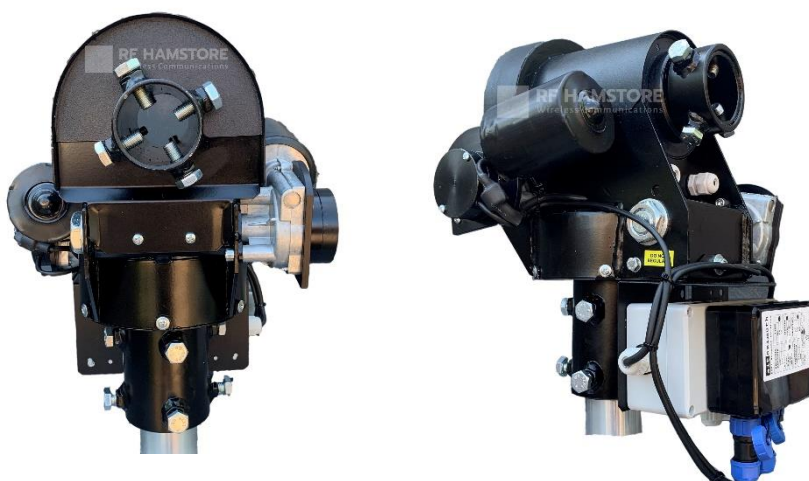
Specifications Rotor Controller, type MD-02

| | |
|----------------------|---|
| Supply voltage input | 13.8 and 24 volt |
| Current consumption | 6.....18 A |
| Supplied with | build in PC track interface (USB), MD01dde.exe controlling software, connectors |
| Dimensions | Desk top housing (386x310x70mm) |
| Weight: | 1.9 Kg |
| Case | Aluminium / steel |
| Environment | Ground / Mobile Sheltered |
| MTBF | 15000 hours @ -5 to +40°C |
| Display | 2* 4 digit (green) |

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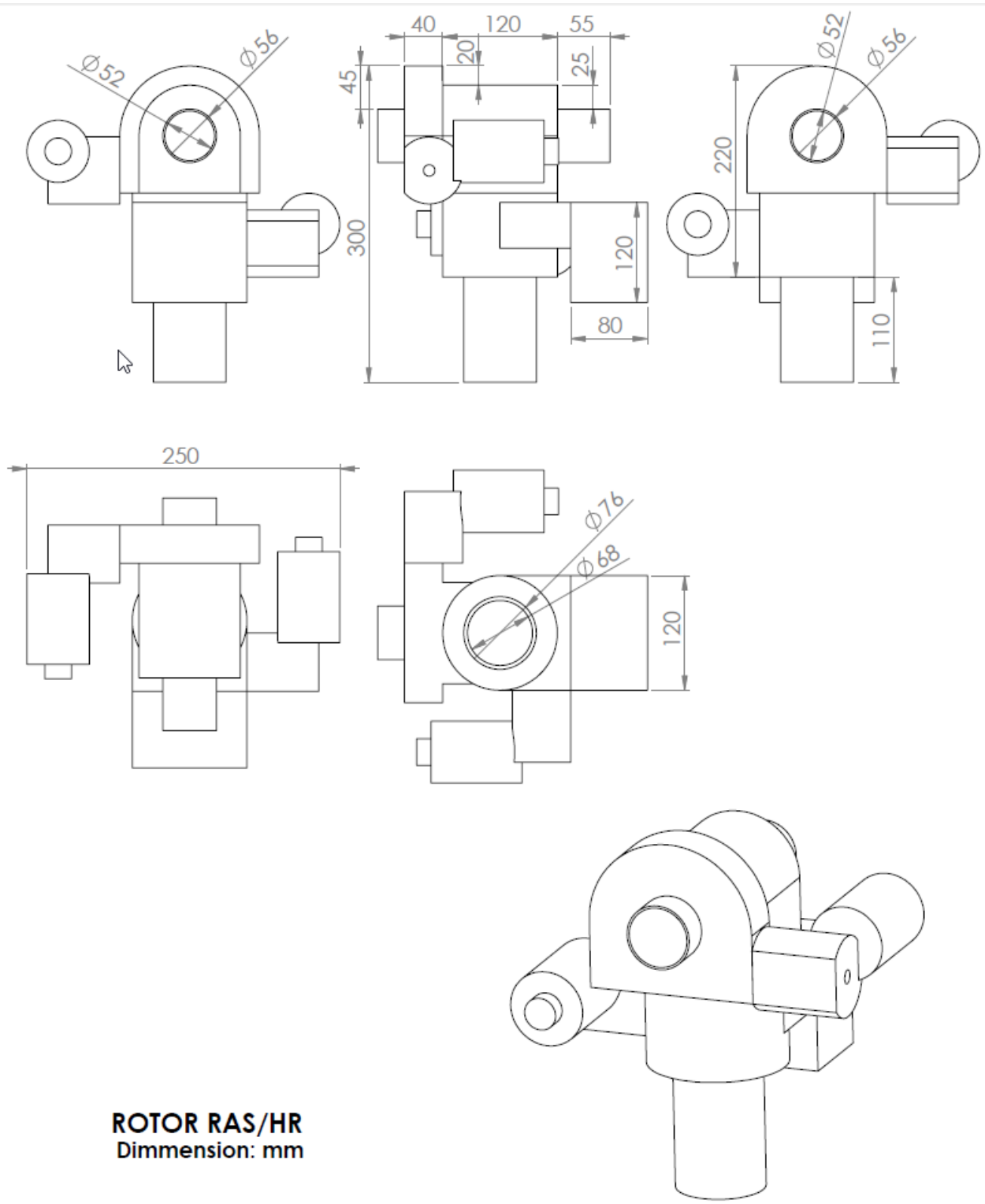
SPID RAS/HR Azimuth & Elevation Rotor



| | |
|--|---|
| Specifications: SPID RAS/HR AZ & EL Rotator | RAS/HR |
| Turning torque in-lbs/Nm | 2734 in lb/ 309 Nm |
| Brake Torque in lbs/Nm | 13985 in lb/ 1580 Nm |
| Brake Construction | Double Worm Gears |
| Vertical Load lbs/Kg | >550 lbs/250 Kg |
| Rotation Speed in Degree AZ | 3.8 degree/sec @ 18V DC (Optional 4.5 degrees/sec, indicate when ordering) |
| Resolution | 0.2 degree |
| Rotation Range AZ / EL | 360 / 180 deg |
| Weight lbs / Mass Kg | 31 lbs/14 Kg |
| Position Sensor | HALL Sensors |
| Position Sensor / control cable connector | IP-68 connector |
| Mast size inches/mm Bottom mount | 2.6 in/66 mm |
| Environment | Ground / Mobile free air and / or Sheltered |
| MTBF | 12500 hours @ -20 to +55°C |
| Control cable Engine | 4-core / 1.5mm ² |
| Control cable Sensors | 6-core / 0.25mm ² |

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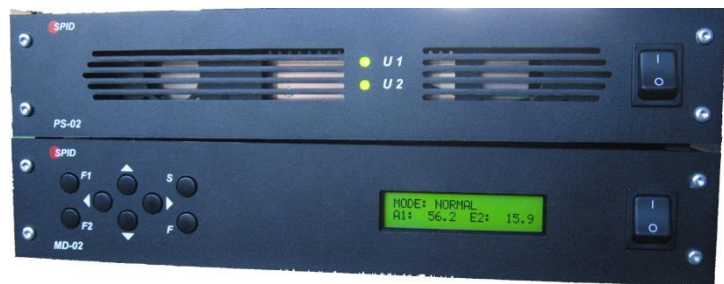
SPID Power Supply Module, PS-02



This Module, PS-02 is a Dual Voltage PSU which should be connected to MD-02

Standard build in is a 15Volt / 10A and a 22Volt / 22A Power Supply unit

It can be easily placed at the MD-02, same dimensions as MD-02






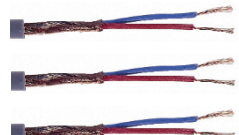




| Specifications: SPID PS-02 power supply | |
|--|---|
| AC input | 50/60Hz – 100-240VAC |
| Dimensions | Desk top housing (386x310x70mm) |
| Weight lbs / Mass Kg | 12,4 lbs / 5,6 Kg |
| Environment | Ground / Mobile free air and / or Sheltered |
| MTBF | 32000 hours @ -20 to +55°C |
| Delivered incl | Connectors and mains cable |

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Available accessories

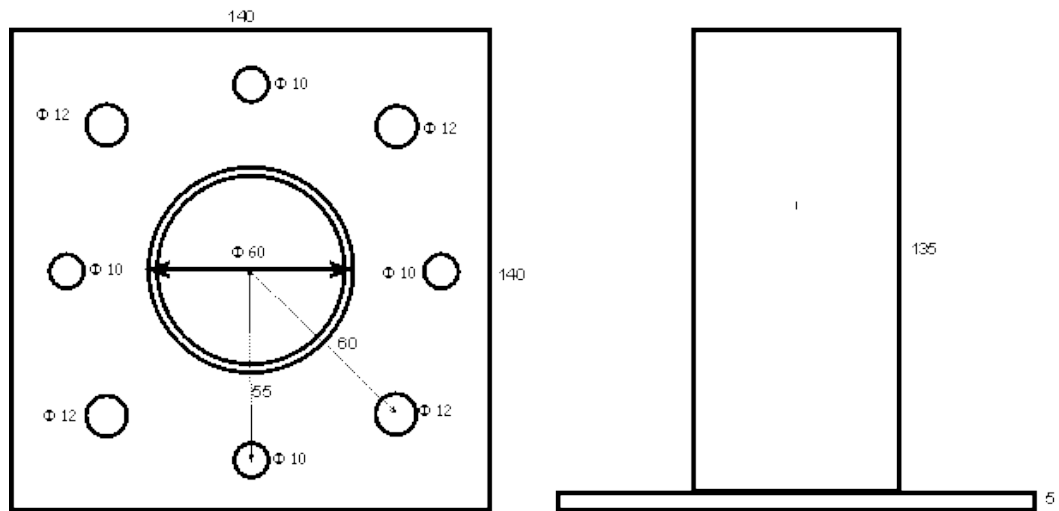
| Accessories | Type | |
|---|-------------------|---|
| <p>Mounting bracket</p> <p>This bracket is delivered incl all ass. Parts and ready to use as a mounting platform or to interface between dish and rotor</p> | FPD-BR02 |  |
| <p>SPID Ethernet Module</p> <p>Remote control Rotor setup through Ethernet (TCP/IP) This unit is supplied ready to place in the MD-01 or MD-02 controller</p> | SPID-ET |  |
| <p>SPID-CCM</p> <p>CCM - CURRENT CONTROL MODULE measurement module to measure Amp's during use direct in MD-0x controllers. (Perfect to find out rotor balance)</p> | SPID-CCM |  |
| <p>Motor Control cable 4-core (4x1,5mm²) (Used for both motors)</p> <p>Reel: 25meter / 50 meter</p> | CC4-002/25 |  |
| <p>Sensor Control Cable Unscreened (6x0,25mm²)</p> <p>Reel: 25 meter max length</p> | CC6-004/25 |  |
| <p>Sensor Control Cable Screened</p> <p>Needed if control cable longer than 25 meter !</p> <p>3 x 2 core screened cable (1x EL / 1x AZ / 1x Power / 0.14mm² each)</p> <p>Available 50 or 100 meter lengths</p> | CC6-003/50 |  |
| <p>SPID ADAPTOR Plate</p> <p>Used to Mount the rotator at a base-plate</p> | SPID-ADAPT |  |
| <p>MOUSE</p> <p>Control AZ & EL movement by mouse connected to MD01</p> | SPID MOUSE |  |

Note: Prices can be found in our price list, download link at our web-site: www.rfhamdesign.com

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Dimension SPID ADAPTOR Plate in mm.



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